

Application Note

15W Multi Output Offline Flyback Transformer

Design Considerations Taken to Achieve over 86% Efficiency for Industrial Appliance Applications



SN015 // SUCHETHAN SWAROOP VAIDYANATH, WÜRTH ELEKTRONIK AND JOHN DOROSA, TEXAS INSTRUMENTS

1 Introduction

Next generation battery chargers used in industrial appliance applications such as power tools often require isolated AC/DC power supplies with high efficiency, low profile, low standby power and small form factor along with multiple outputs. The UCC28711 flyback power supply controller provides isolated outputs without the use of an optical coupler. This translates into fewer number of components on the board. This controller processes information from the auxiliary flyback winding for precise control of output voltage and current. Quasi resonant mode with valley switching reduces switching losses. The primary side MOSFET turns on during the first valley at maximum load. The UCC28711 has a maximum switching frequency of 100 kHz and always maintains control of the primary peak current in the transformer. Texas Instrument's reference design PMP21927 takes a universal VAC input and creates three isolated 15 V outputs. The main output can be loaded up to 1 A and achieves over 86% efficiency. The other two isolated 15 V outputs can be loaded to 50 mA each. Using primary side regulation usually gives +/-5% regulation accuracy related to the output voltage and normally it is avoided when multiple outputs are involved. In this design, the low current outputs have LDO linear regulators to keep the voltages within 1% regardless of cross-loading conditions. The transformer is a principal component in such designs. Building a transformer is often an iterative process with many incremental changes that can affect the overall efficiency. In this application note, we will focus on the flyback transformer design with multi-isolated outputs used in PMP21927 and discuss the many design considerations taken to achieve high efficiency while maintaining a low profile part for power tool applications.

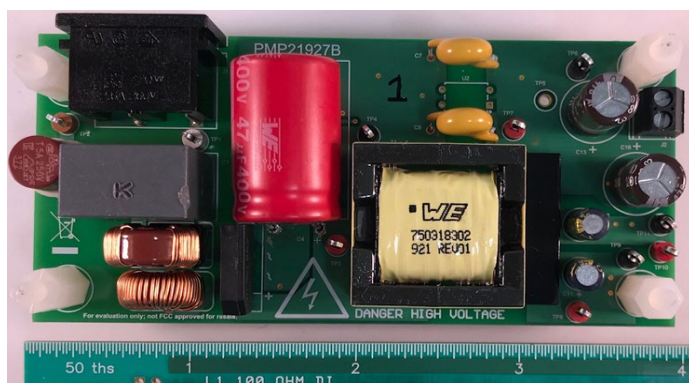


Figure 1: Top view of PMP21927 15W multi output offline flyback reference design board

2 Design parameters of 15 W QR offline flyback transformer with three outputs

- Input voltage range : 85-265 VAC
- Output 1: 15 V / 1 A
- Output 2 and Output 3: 15 V / 50 mA after regulation (16.7 V before regulation)
- Auxiliary (bias) output: 18 V / 20 mA
- Frequency of operation: 70 to 80 kHz
- Safety standard : UL60950-1 with reinforced insulation

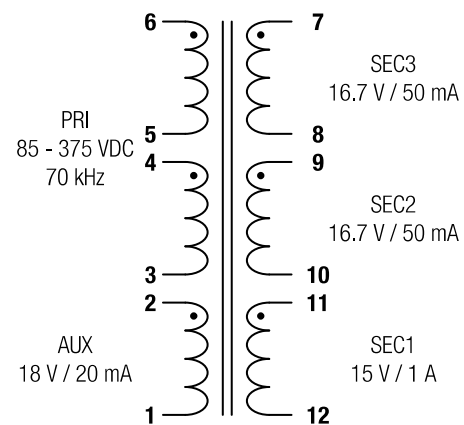


Figure 2: 750318302 transformer windings

The maximum available duty cycle (D_{max}) is based on discontinuous conduction mode (DCM), resonant time (t_R), target switching frequency at max load (F_{max}) and demagnetizing duty cycle (D_{magcc}). Demagnetizing duty cycle is the secondary diode conduction duty cycle during constant-current operation and it is set internally by the UCC2871x family to 0.425. All equations listed in sections 2 through 8 are referenced from TI's UCC2871x controller family datasheet.

The equation for maximum duty cycle is as follows:

$$D_{max} = 1 - \left(\frac{t_R}{2} \cdot F_{max} \right) - D_{magcc} = 1 - \left(\frac{2 \mu s}{2} \cdot 80 \text{ kHz} \right) - 0.425$$

$$D_{max} = 0.495 \text{ or } 49.5 \%$$

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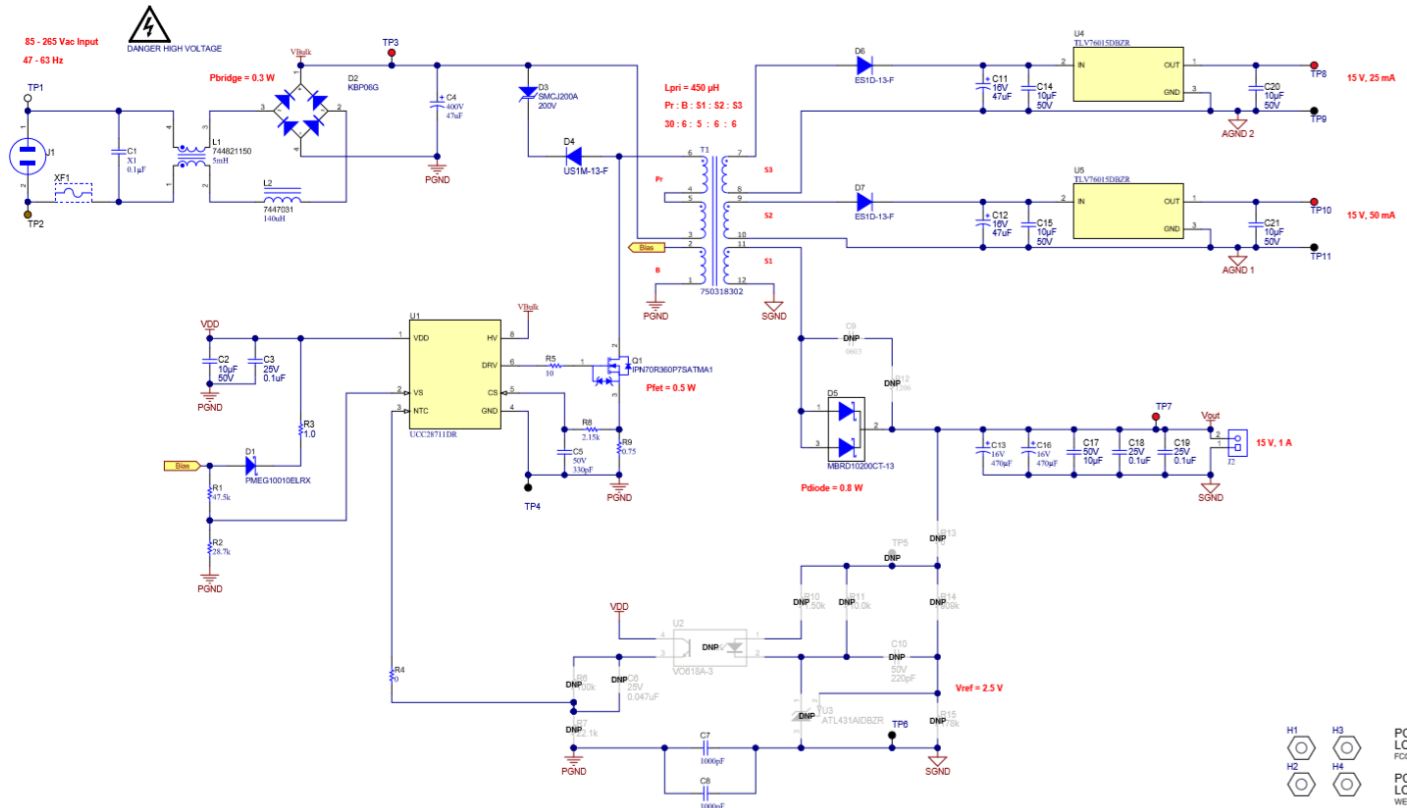


Figure 3: 15W multi-output offline flyback reference design schematic

3 Primary to secondary turns ratio calculation

Since we have three outputs, we will use the output with the highest power of 15 V / 1 A as a starting point to calculate the turn's ratios. Note that this can be an iterative process since multiple outputs are involved. The maximum primary to secondary turns ratio, N_{PS1} is calculated at the maximum frequency at full load, along with estimated DCM resonant time, minimum input capacitor bulk voltage ($V_{bulkmin}$), regulated output voltage (V_{ocv}), secondary rectifier forward voltage drop at near zero current (V_f) and target cable compensation voltage at the output terminals (V_{ocbc}).

$$N_{PS1max} = \frac{D_{max} \cdot V_{bulkmin}}{D_{magcc} \cdot (V_{ocv} + V_f + V_{ocbc})}$$

$$N_{PS1max} = \frac{0.495 \cdot (85 V \cdot 1.414 \cdot 0.7)}{0.425 \cdot (15 V + 0.5 V + 0)} = 6.3$$

We will round down $N_{PS1max} = 6$.

4 Other secondary windings turns ratio calculation

The turns ratio of the additional secondary windings is based on the regulated secondary and can be calculated using a simple ratio.

$$N_{S2S1} = \frac{V_{outS2} + V_f}{V_{outS1} + V_f} = \frac{16.7 V + 0.5 V}{15 V + 0.5 V} = 1.11$$

The turns ratio of secondary 3 is same as secondary 2 with the actual turns rounded up to the next full turn.

5 Auxiliary winding to secondary winding turns ratio calculation

The bias supply from the auxiliary winding is used for voltage sensing and powering the IC. Hence, the winding is kept on the same side of the bobbin as the primary winding. The auxiliary winding also operates at the same time as the secondary windings. The turns ratio (N_{AS1}) is calculated using the bias supply undervoltage lockout (V_{ULO}) voltage ($V_{Doff} = 7.35 V$) which is a device parameter, auxiliary rectifying diode forward voltage drop ($V_{fa} = 0.7 V$), minimum desired output voltage during constant current mode ($V_{occ} = 6.09 V$) and the forward voltage drop of output rectifying diode ($V_f = 0.5 V$). There is additional energy

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supplied to VDD from the transformer leakage inductance which allows a lower turns ratio to be used in many designs.

$$N_{AS1} = \frac{V_{DD_{off}} + V_{fa}}{V_{OCC} + V_f} = \frac{7.35 \text{ V} + 0.7 \text{ V}}{6.09 \text{ V} + 0.5 \text{ V}} = 1.22$$

6 Current sense resistor calculation

The transformer turns ratio and UCC2871x constant-current regulating voltage (V_{ccr}) determine the current sense resistor for a target current ($I_{occ} = 1.3 \text{ A}$). As not all of the energy stored in the transformer is transferred to the secondary, the transformer efficiency term is included. At the design phase, we assume 3.5 % leakage inductance, 5% core and winding losses, and 1.5 % bias power losses, for an overall transformer efficiency factor of $\eta = 0.9$ or 90 %.

$$R_{CS} = V_{ccr} \cdot N_{PS1} \cdot \frac{\sqrt{\eta}}{2 \cdot I_{occ}} = 343 \text{ mV} \cdot 6 \cdot \frac{\sqrt{0.9}}{2 \cdot 1.3 \text{ A}} = 0.750 \Omega$$

We will select a current sense resistor with $R_{CS} = 0.75 \Omega$.

7 Primary and secondary peak currents calculation

Peak currents are important in calculating the required primary inductance needed in the transformer. Primary peak current is simply the maximum current sense threshold at the controller (V_{cstmax}) divided by the current sense resistance (R_{CS}).

$$I_{ppmax} = \frac{V_{cstmax}}{R_{CS}} = \frac{0.773 \text{ V}}{0.75 \Omega} = 1.0307 \text{ A}$$

The secondary peak current (I_{spmax}) is the primary peak current (I_{ppmax}) multiplied by turns ratio (N_{PS1}) of the transformer.

$$I_{spmax} = I_{ppmax} \cdot N_{PS1} = 1.0307 \text{ A} \cdot 6 = 6.184 \text{ A}$$

The peak current of secondary 2 can be calculated using these equations:

$$L_{S2} = \frac{L_P}{N_{PS2}^2} = \frac{450 \mu\text{H}}{5.4^2} = 15.432 \mu\text{H}$$

$$\text{where } N_{PS2} = N_{PS1}/N_{S2S1} = 6/1.11 = 5.4$$

and $L_P = 450 \mu\text{H}$, calculated in the next section.

$$P_{O2} = P_{O3} = 16.7 \text{ V} \cdot 50 \text{ mA} = 0.835 \text{ W}$$

$$I_{pkS2} = \sqrt{\frac{P_{O2}}{F_{max} \cdot L_{S2}}} = \sqrt{\frac{0.835 \text{ W}}{80 \text{ kHz} \cdot 15.432 \mu\text{H}}} = 0.82 \text{ A}$$

8 Primary inductance calculation

The primary inductance of the transformer (L_P) is calculated using the standard energy storage equation for inductors ($E = \frac{1}{2} L \cdot I^2$). The parameters required are primary peak current (I_{pp}), maximum switching frequency (F_{max}), total power (P_{out}) and transformer efficiency (η).

$$P_{out} = (15 \text{ V} \cdot 1 \text{ A}) + 2(16.7 \text{ V} \cdot 50 \text{ mA}) + (18 \text{ V} \cdot 20 \text{ mA})$$

$$P_{out} = 17.03 \text{ W}$$

$$L_P = \frac{2 \cdot P_{out}}{\eta \cdot I_{ppmax}^2 \cdot f_{max}} = \frac{2 \cdot 17.03 \text{ W}}{0.9 \cdot (1.03 \text{ A})^2 \cdot 80 \text{ kHz}} = 445.9 \mu\text{H}$$

We shall select $L_P = 450 \mu\text{H}$ considering +/-10 % of tolerance.

9 Primary and secondary rms currents calculation

The primary and secondary rms currents are important to find the right wire sizes in the transformer.

Primary rms current (I_{rmspri}) is dependent on peak current (I_{pp}) and maximum duty cycle (D_{max}).

$$I_{rmspri} = I_{ppmax} \cdot \sqrt{\frac{D_{max}}{3}}$$

$$I_{rmspri} = 1.0307 \text{ A} \cdot \sqrt{\frac{0.495}{3}} = 0.42 \text{ A}$$

The equation for secondary rms current (I_{rmssec}) is dependent on secondary peak current (I_{spmax}) and demagnetizing duty cycle (D_{magcc}).

$$I_{rmssec1} = I_{spmax} \cdot \sqrt{\frac{D_{magcc}}{3}}$$

$$I_{rmssec1} = 6.184 \text{ A} \cdot \sqrt{\frac{0.425}{3}} = 2.33 \text{ A}$$

The rms currents on secondary 2 and secondary 3 windings can be calculated using these equations:

$$I_{dc} = I_{pk} \frac{D}{2}, \quad I_{rms} = I_{pk} \sqrt{\frac{D}{3}}$$

I_{S2} and I_{S3} are the maximum output DC currents and D_{offS2} is the estimated duty cycle of the off time for the secondary 2 and 3 windings.

$$D_{offS2} = \frac{2 \cdot I_{S2}}{I_{pkS2}} = \frac{2 \cdot 50 \text{ mA}}{1.16 \text{ A}} = 8.62\%$$

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As we know the peak current and duty cycle, we can calculate the total rms current for the second and third windings.

$$I_{\text{rms sec2}} = I_{\text{pkS2}} \cdot \sqrt{\frac{D_{\text{offS2}}}{3}} = 0.82 \cdot \sqrt{\frac{0.086}{3}} = 0.14 \text{ A}$$

10 Selection of the core and bobbin

For power applications below 500 kHz, Manganese-Zinc (Mn-Zn) ferrite material is preferred for cores as it has good performance with permeability (μ_r) from 2000 to 2500. TP4A core material is used in this design. Its saturation flux density (B_{sat}) is 390 mT at 100 °C. There are many core shapes available such as EE, EFD, EP, RM, PQ, ETD etc. The following parameters need to be taken into consideration while choosing the core and the bobbin:

- Volume of the core needed
- Size constraints such as low profile or footprint
- Safety standards needed to be met
- Insulation requirements (functional or reinforced)
- Power that the core can handle at given frequency
- Through hole or surface mount
- Vertical or horizontal package
- Number of pins needed on the bobbin

Calculating total input power P_{in}

$$P_{\text{in}} = \frac{P_{\text{out}}}{\eta} = \frac{17.03 \text{ W}}{0.9} = 18.92 \text{ W}$$

We shall use the below equation to determine the effective volume of the core (V_e) needed. This equation is derived from the book: "Switching Power Supplies A-Z" by Sanjaya Maniktala.

$$V_{e\text{cm}^3} = \frac{31.4 \cdot P_{\text{in}} \cdot \mu_r}{z \cdot f_{\text{MHz}} \cdot B_{\text{sat}}^2} \left(r \cdot \left(\frac{2}{r} + 1 \right)^2 \right)$$

Relative permeability (μ_r) is set to 2000. The maximum flux density (B_{sat}) is set to 300 mT to provide margin. One of the most important considerations in flyback transformer design is not to saturate the transformer. The core air gap factor (z), $AL_{\text{nogap}}/AL_{\text{gapped}}$ is set to 10 and current ripple ratio (r), $\Delta I/I$ is set to 0.4.

$$V_e = \frac{31.4 \cdot 18.92 \cdot 2000}{10 \cdot 0.08 \cdot 3000^2} \left(0.4 \cdot \left(\frac{2}{0.4} + 1 \right)^2 \right) = 2.37 \text{ cm}^3$$

From Würth Elektronik's Custom Capabilities Catalog, the core volume of EFD25 package is 3.3 cm³. The core volume of EFD20 package is 1.46 cm³. Hence, we will choose EFD25 through whole package as it meets the core volume criteria of 2.37 cm³ and other requirements such as low profile height, an extended rail to meet the safety standards and 12 pins needed for multiple outputs.

11 Transformer wire sizes and construction

Based on thermal considerations, we choose the current density (J) to be 10 A/mm² as mentioned in the book: "Optimal Design of Switching Power Supply" by Zhanyou Sha et al. The wire sizes are selected as below:

$$\text{PRI (wire cross sectional area)} = \frac{I_{\text{rms pri}}}{J} = \frac{0.42 \text{ A}}{10 \text{ A/mm}^2} = 0.042 \text{ mm}^2$$

with equivalent minimum diameter of 0.23 mm for primary windings.

$$\text{SEC (wire cross sectional area)} = \frac{I_{\text{rms sec}}}{J} = \frac{2.33 \text{ A}}{10 \text{ A/mm}^2} = 0.233 \text{ mm}^2$$

with equivalent minimum diameter of 0.54 mm for secondary windings.

We need to choose the wire diameter to be less than twice of the skin effect depth for proper utilization of copper. The skin depth at 100 °C in millimeters can be calculated as follows:

$$\text{Skin depth} = \frac{76}{\sqrt{f}} = \frac{76}{\sqrt{80000}} = 0.269 \text{ mm}$$

The wire diameter should be less than twice the skin depth or 0.538 mm. Taking all of these parameters into consideration, 0.32 mm diameter wire (28 AWG) is chosen for primary and auxiliary windings. 0.53 mm diameter wire (23.5 AWG) is chosen for secondary windings. Thicker wire is preferred as it provides lower resistance. For the low current secondaries (2,3) 0.10 mm diameter wire (38 AWG) is chosen.

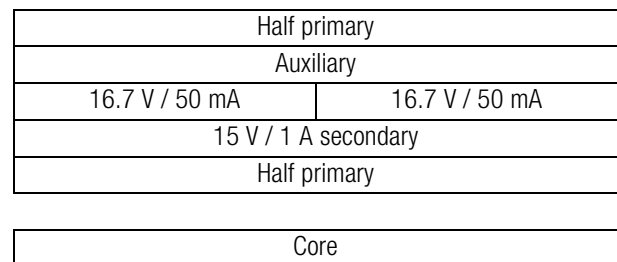


Figure 3: 750318302 construction diagram

Since there are more turns on the primary side, the primary is split to get better coupling and decrease overall leakage inductance. Half the primary winding is wound first, followed by the 15 V / 1 A secondary winding and both 16.7 V / 50 mA secondary windings. The auxiliary winding is wound next and finally the other half primary. There are layers of tape separating each winding. Triple insulated wire is used on the three secondary windings and standard magnet wire is used on the primary and auxiliary windings. This is done for two reasons. First, to keep the costs low as TIW wire is more expensive than magnet wire and there are fewer turns on the secondary windings. The second reason is to reduce the overall fill rate. The creepage and clearance distances are met as defined in UL60950-1 for reinforced insulation at a working voltage of 265 Vrms, overvoltage category II and a pollution degree 2

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environment. Varnish is used to secure the core and windings in place and prevent ingress of moisture in the transformer. It also improves the thermal conductivity by aiding in transfer of heat from windings to free air and helps in sustaining dielectric capabilities as well.

12 Estimate losses

Core loss can be estimated using Figure 3. Since this application uses a uni-polar waveform, and the chart in Figure 3 is applicable to bi-polar waveforms with B_{max} as peak to peak, we must divide the magnetic flux density in half to use the charts. In section 11 we chose a maximum magnetic flux density of 300 mT for the core. Dividing this in half gives 150 mT. Using the 100 kHz curve from Figure 3, at 150 mT there is an approximate core loss per volume of 150 mW/cm³ (Note: mW/cm³ is the same as kW/m³ scaled by 10⁻⁶). Multiplying this value with the core volume of EFD25 package, 3.306 cm³, gives us the approximate core loss.

$$P_{core} = 150 \frac{\text{mW}}{\text{cm}^3} \cdot 3.306 \text{ cm}^3 = 496 \text{ mW}$$

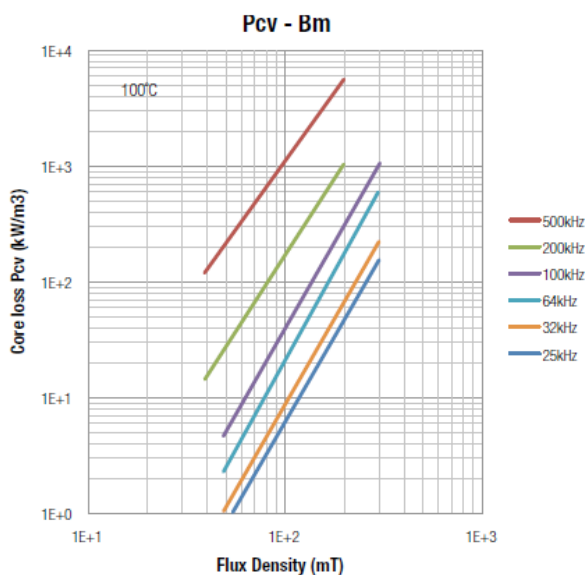


Figure 4: Flux density vs Core loss for TP4A material. Note that core loss units can be scaled by 10⁻⁶ to give mW/cm³

Simple copper loss can be estimated using $I_{rms}^2 \cdot DCR$. The rms currents are calculated in section 10. The DCR values are calculated from the average turn length and the wire resistance.

$$P_{cu} = P_{pri1} + P_{pri2} + P_{sec1} + P_{sec2} + P_{sec3} + P_{aux}$$

$$P_{cu} = ((0.42 \text{ A})^2 \cdot 0.290 \Omega) + ((0.42 \text{ A})^2 \cdot 0.290 \Omega) + ((2.33 \text{ A})^2 \cdot 0.031 \Omega) + 2 ((0.2 \text{ A})^2 \cdot 1.038 \Omega) + ((0.031 \text{ A})^2 \cdot 0.117 \Omega)$$

$$P_{cu} = 381 \text{ mW}$$

Total transformer loss = $P_{core} + P_{cu} = 887 \text{ mW}$

Transformer efficiency can be calculated as:

$$\eta = 1 - \left(\frac{0.877 \text{ W}}{17.03 \text{ W}} \right) = 94.85 \%$$

13 Temperature rise

A simple and fast estimate of temperature rise can be made by looking up the R_{th} of the core which represents the temperature rise for one watt of losses. For the EFD25 core, $R_{th} = 30 \text{ K/W}$. Multiplying by the total losses gives the temperature rise above ambient.

$$T_{rise} = R_{th} \cdot P_{losses} = 30 \cdot 0.877 = 26.3 \text{ }^\circ\text{C}$$

14 Testing and efficiency graphs

The overall board efficiency was measured by loading the main 15 V output. The other two 15 V outputs were loaded to 50 mA and kept in regulation by the LDOs.

P_{IN} (W)	V_{OUT} (V)	I_{OUT} (A)	P_{OUT} (W)	Efficiency (%)	P_{LOSS} (W)
0.8430	15.0487	0.0445	0.6697	79.44	0.1733
4.3555	15.0240	0.2500	3.7560	86.24	0.5995
8.6366	15.0336	0.4980	7.4867	86.69	1.1499
13	15.0309	0.7490	11.2581	86.60	1.7419
17.3	15.0361	1	15.0361	86.91	2.2640

Table 2: Efficiency data for 120 VAC input

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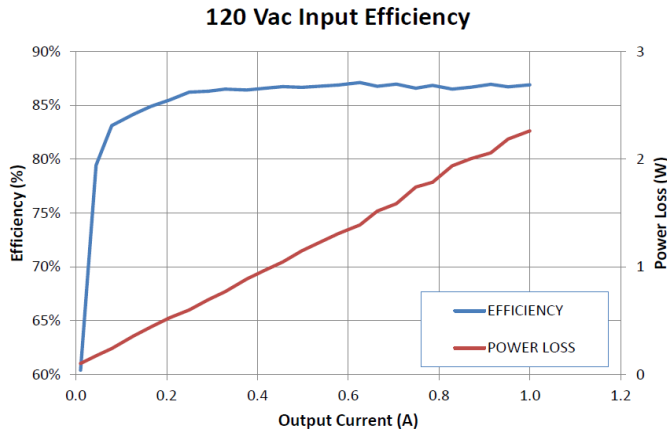


Figure 5: Total board efficiency graph with 120 VAC input

P_{IN} (W)	V_{OUT} (V)	I_{OUT} (A)	P_{OUT} (W)	Efficiency (%)	P_{LOSS} (W)
0.9160	15.0410	0.0451	0.6784	74.06	0.2376
4.4599	15.0265	0.2500	3.7566	84.23	0.7033
8.6973	15.0237	0.4980	7.4818	86.02	1.2155
13	15.0385	0.7480	11.2488	86.53	1.7512
17.3	15.0427	.9990	15.0276	86.87	2.2724

Table 3: Efficiency data for 230 VAC input

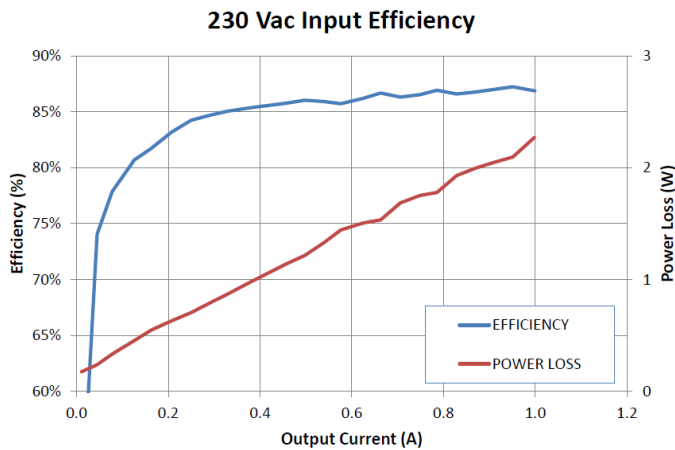


Figure 6: Total board efficiency graph with 230 VAC input

15 Conclusion

We had initially assumed 90% as the efficiency of our transformer during our design calculations considering 3.5 % leakage inductance losses, 5 % core and winding losses and 1.5 % bias power losses. We have calculated 5.15 % of loss from core and DC winding losses (estimated 6.5 % from all core and winding losses, including AC winding losses, which we didn't calculate). Going with 90 % transformer efficiency during design phase for calculations for a three output flyback transformer is a very good estimate. AC losses and bobbin fill factor should be taken into consideration as well. As mentioned earlier, building a flyback transformer is an iterative process but these above guidelines should lessen the number of iterations and get us an optimum solution in about two revisions. On a system level, this 15 W multi-output, offline flyback design achieved over 86% efficiency, taking switching losses and other component losses into consideration.

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A. Appendix

A.1. References

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CONTACT INFORMATION

appnotes@we-online.com

Tel. +49 7942 945 - 0



Würth Elektronik eiSos GmbH & Co. KG

Max-Eyth-Str. 1 · 74638 Waldenburg · Germany



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